

The Exponential of a Matrix

The exponential of the $n \times n$ matrix A is the $n \times n$ matrix

$$e^A = I + A + \frac{1}{2!} A^2 + \frac{1}{3!} A^3 + \cdots = \sum_{k=0}^{\infty} \frac{1}{k!} A^k.$$

Properties

- The solution to the initial value problem

$$\mathbf{x}' = A\mathbf{x} \quad \mathbf{x}(0) = \mathbf{x}_0$$

is given by $\mathbf{x}(t) = e^{tA}\mathbf{v}$, where e^{tA} is the exponential of the t -dependent matrix tA .

- If λ is an eigenvalue of A and \mathbf{v} an eigenvector (i.e. $(A - \lambda I)\mathbf{v} = 0$), then

$$e^{tA}\mathbf{v} = e^{\lambda t}\mathbf{v}.$$

Generalized eigenvectors. We say that a vector \mathbf{v} is a generalized eigenvector for the eigenvalue λ if there exists a number $k > 1$ such that $(A - \lambda I)^k \mathbf{v} = 0$. One can show that if \mathbf{v} is a generalized eigenvector, then

$$e^{tA}\mathbf{v} = e^{\lambda t} \left(\mathbf{v} + t(A - \lambda I)\mathbf{v} + \frac{t^2}{2!}(A - \lambda I)^2\mathbf{v} + \cdots + \frac{t^{k-1}}{(k-1)!}(A - \lambda I)^{k-1}\mathbf{v} \right).$$

These properties help us find sufficient fundamental solutions for the linear system $\mathbf{x}' = A\mathbf{x}$. Recall that in the case of a repeated eigenvalue (of algebraic multiplicity m) we might not have m linearly independent eigenvectors. This happens when the dimension of the nullspace of $A - \lambda I$ (called the geometric multiplicity of λ) is strictly less than the arithmetic multiplicity m . However, the mathematical theory says that one can complete the necessary number with linearly independent generalized eigenvectors. More precisely, there exists a power $k \leq m$, such that the nullspace of $(A - \lambda I)^k$ has dimension m , hence one can find m linearly independent generalized eigenvectors. These generalized eigenvectors will provide the necessary fundamental solutions for our linear system.

Procedure for λ an eigenvalue of algebraic multiplicity m

To find m linearly independent solutions associated with λ :

- Find the smallest integer $k \leq m$ such that $\text{null}(A - \lambda I)^k$ has dimension m .
- Find a basis $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ of $\text{null}(A - \lambda I)^k$.
- For $j = 1, 2, \dots, m$ compute the fundamental solutions

$$\mathbf{x}_j(t) = e^{tA}\mathbf{v}_j = e^{\lambda t} \left(\mathbf{v}_j + t(A - \lambda I)\mathbf{v}_j + \frac{t^2}{2!}(A - \lambda I)^2\mathbf{v}_j + \cdots + \frac{t^{k-1}}{(k-1)!}(A - \lambda I)^{k-1}\mathbf{v}_j \right)$$

Example.

$$A = \begin{bmatrix} 1 & 2 & -1 \\ -4 & -7 & 4 \\ -4 & -4 & 1 \end{bmatrix}$$

The characteristic polynomial is

$$p(\lambda) = \det(A - \lambda I) = -(\lambda + 3)(\lambda + 1)^2,$$

hence the eigenvalues are $\lambda = -3$ and $\lambda = -1$ (with algebraic multiplicity 2).

For $\lambda = 3$: we find a corresponding eigenvector by solving $(A - 3I)\mathbf{v} = 0$. One gets, for example, $\mathbf{v}_1 = [-1, 3, 2]^T$. This gives us one fundamental solution

$$\mathbf{x}_1(t) = e^{3t} \begin{bmatrix} -1 \\ 3 \\ 2 \end{bmatrix}.$$

For $\lambda = 1$: solving for $(A - I)\mathbf{v} = 0$, we obtain a one-dimensional eigenspace spanned by $\mathbf{v}_2 = [-1, 2, 2]^T$. Hence a fundamental solution is given by

$$\mathbf{x}_2(t) = e^t \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}.$$

We need a third solution. For this, we compute the nullspace of $(A - \lambda I)^2$ and find that it has dimension 2. Since the eigenvector \mathbf{v}_2 is also in the nullspace of $(A - \lambda I)^2$, we must choose a vector \mathbf{v}_3 in $\text{null}(A - \lambda I)^2$ which is not a multiple of \mathbf{v}_2 . For example $\mathbf{v}_3 = [1, 0, 0]^T$, and this gives us a third solution

$$\mathbf{x}_3(t) = e^t (\mathbf{v}_3 + t(A + I)\mathbf{v}_3) = e^t \begin{bmatrix} 1 + 2t \\ -4t \\ -4t \end{bmatrix}.$$

In conclusion the general solution of $\mathbf{x}' = A\mathbf{x}$ is given by

$$\mathbf{x}(t) = c_1\mathbf{x}_1(t) + c_2\mathbf{x}_2(t) + c_3\mathbf{x}_3(t).$$